Short-range radionuclide dispersion and deposition modelling

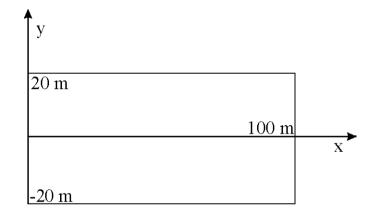
University of Seville model

EMRAS-2

Model characteristics

- Model specifically designed and developed for the exercise
- Lagrangian dispersion model: 10000 particles released
 - 5000 liquid particles
 - 5000 gas particles
- Each particle contains an amount of Bq depending on activity in explosive and on fractionation between liquid and gas
- The model does not try to reproduce the explosion itself, but dispersion just after it
- Differences between liquid and gas particles:
 - Initial conditions
 - Dispersion processes

Geometry of model domain



•Explosion site: origin of coordinates

•z axis directed upwards

•Results are provided on the rectangular box

Liquid particles

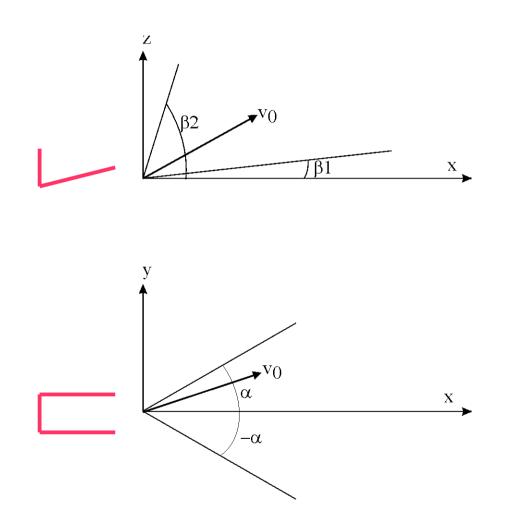
- •Dispersion processes:
 - Parabolic motion with air friction given an initial position and velocity of each particle
 - Advection with wind

•Initial position: anywhere within the explosive shielding (Monte Carlo method)

•Initial velocity:

- A mean value v0 (m/s) and error (%) are introduced as input data
- It is assumed that v0 magnitude obeys a normal distribution with the given mean value and standard deviation
- The actual value for a given particle is obtained from a Monte Carlo method
- The direction of v0 is limited by the explosive shielding (opened on one side and top):

Liquid particles



The actual direction is again obtained from a Monte Carlo method (all possible angles have the same probability)

Gas particles -2 m

•Initial positions: particles form a cloud over the explosion site at an effective height ± 2 m. The actual position for a given particle is obtained from a Monte Carlo method (all positions have the same probability)

•Dispersion:

- Advection by wind
- Turbulent diffusion (Monte Carlo method)

•Radioactive decay (liquid and gas particles): Monte Carlo method

Summary of model parameters

- Calibrated:
 - Initial velocity and error for liquid particles
 - Friction coefficient with air
 - Effective release height for gas particles
 - Fraction of activity released as aerosol (some indications are given in the scenario description)
- Standard values:
 - Turbulent diffusion coefficient in air
 - Radioactive decay constant
 - Dose conversion factor

Summary of model parameters

- From scenario:
 - Horizontal angle α
 - Vertical angles $\beta 1$ and $\beta 2$
 - Wind velocity components
 - Explosive shielding dimensions
 - Activity in explosive
 - Time from activity determination to explosion
- Simulation inputs:
 - Time step for model integration
 - Simulation time

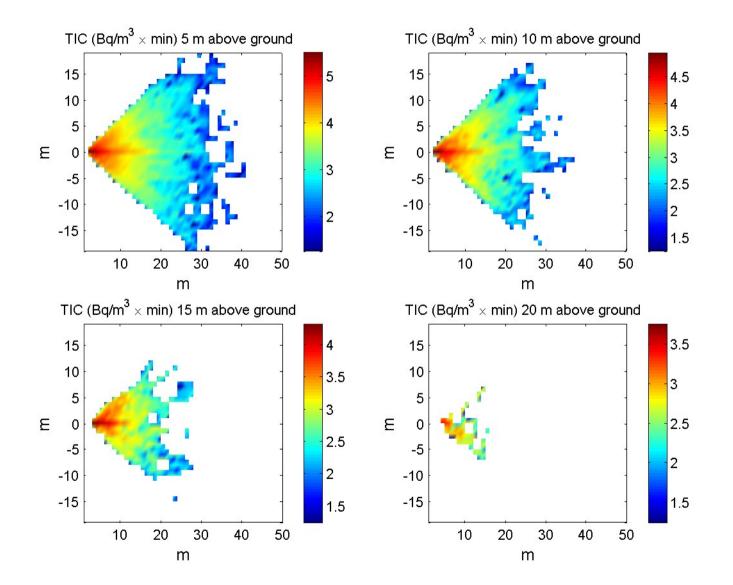
Example of input file

input data for explosion code: test2 12.,40. initial particle velocity (m/s), tolerance (%) initial horizontal dispersion angle 40. 30.,90. vertical angles wind velocity components (m/s) 0.93.0. 0.001 friction coefficient of liquid particles with air 30. diffusion coefficient in air (m^2/s) 100 simulated time (sec) .01 time step (s) box explosive dimensions x,y (m) .80,.50 1058.e6 total activity (Bq) radioactive decay constant (s-1) 3.20e-5 80. time in minutes from activity determination to explosion

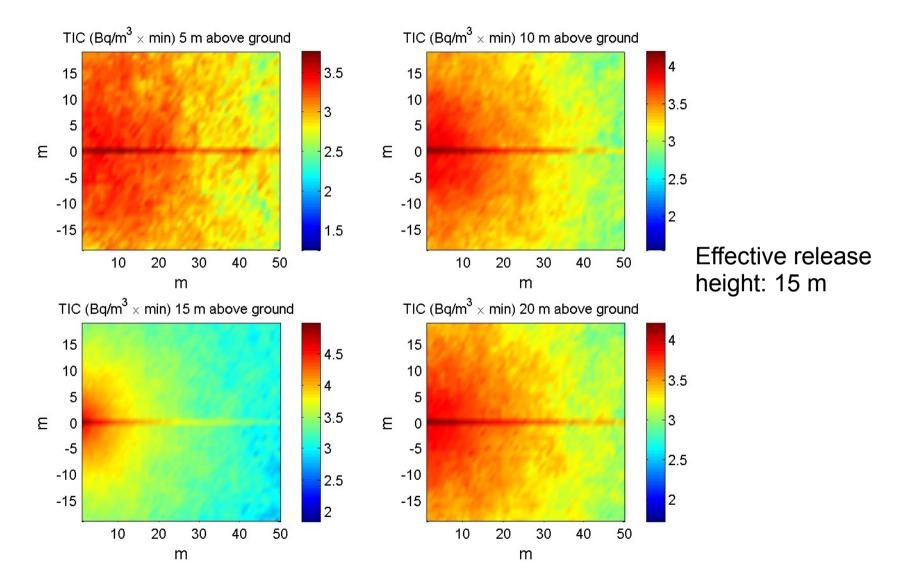
Model output

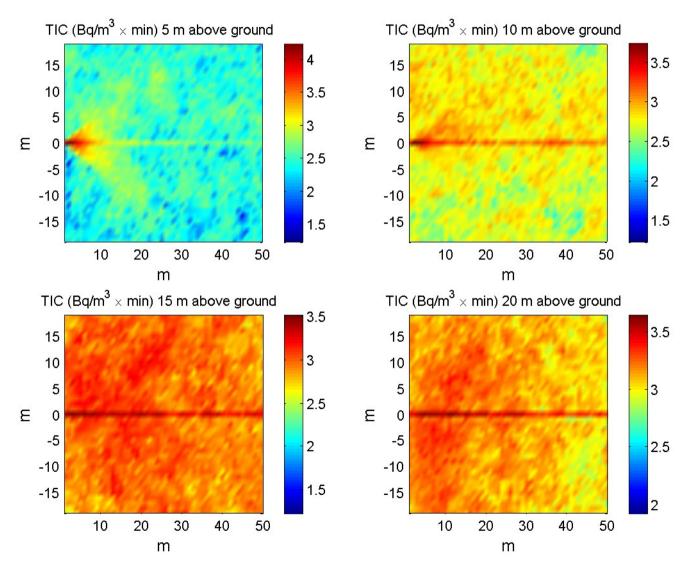
- Deposited activity on the ground on a 1×1 m grid
- Dose rates on the same grid (USEPA report EPA-402-R-93-081)
- Time integrated concentrations in air on the same grid and as function of height (1 m resolution) up to 30 m
- Requested results:
 - 50, 75 and 95 percentiles of total deposited activity (radius of a circle containing such fraction)
 - Surface contamination and dose rates on a 5×5 m grid
 - Time integrated air concentrations along centerline over 5 m intervals and as a function of height

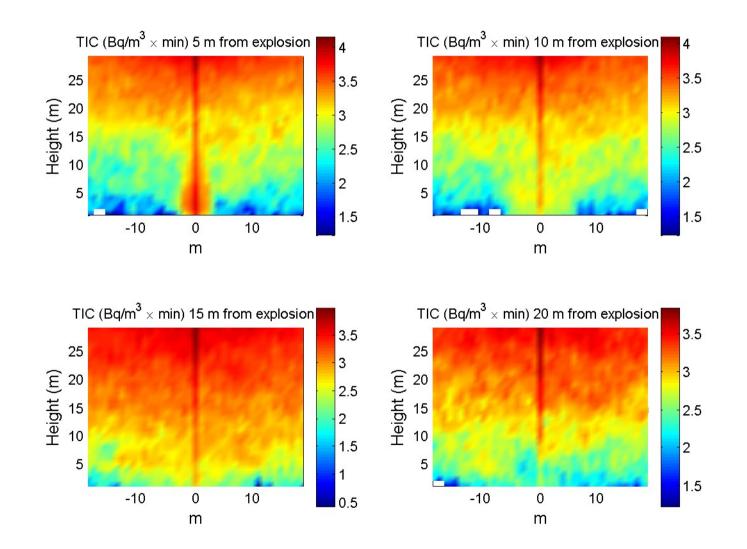
100% of activity in liquid particles

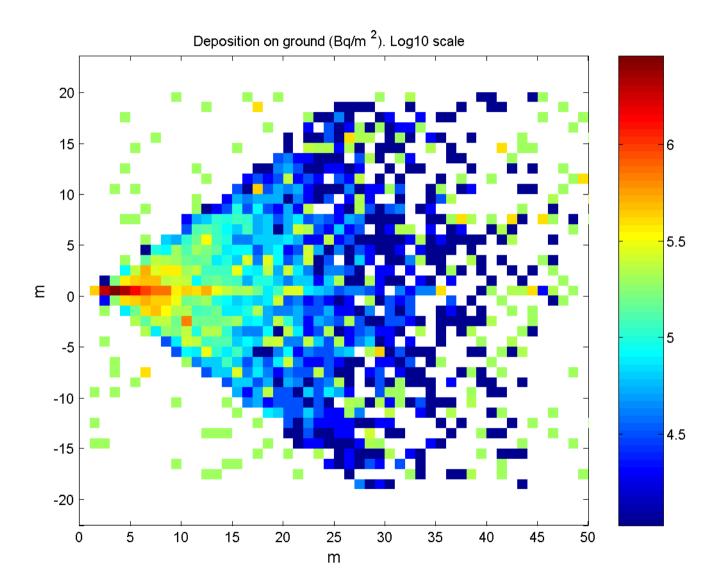


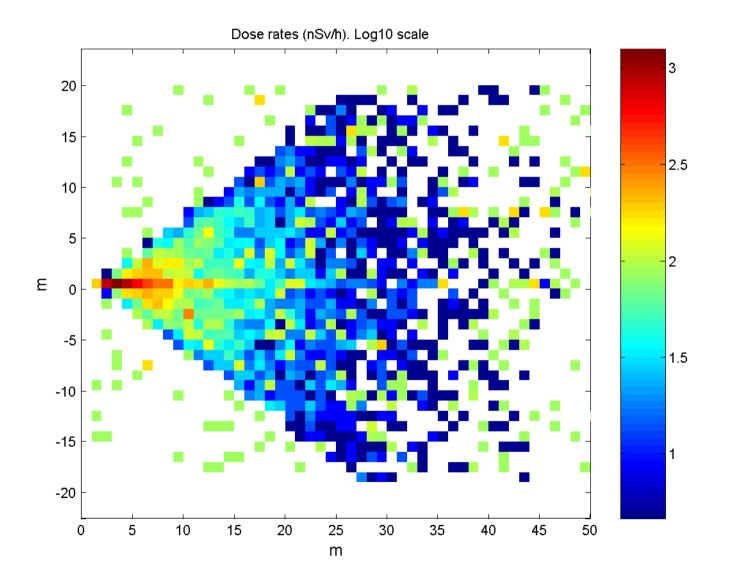
100% of activity in aerosol fraction

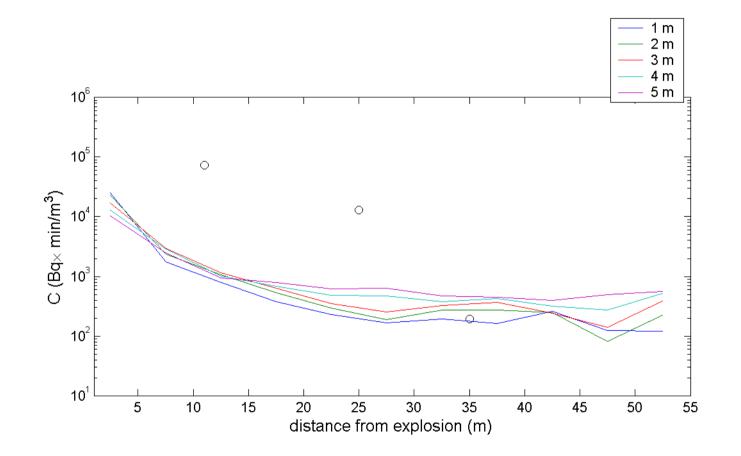












Time integrated air concentrations along centerline over 5 m intervals